no.: Date of issue: 01-07-2015 Definition Manufacturer				
Definition		Rev.:		Page:
	Data	0 Unit	Remarks	1
	Data Dani-tech A/S	Unit	Remarks	
Product	electric motor			
Product code	2802			
ype/Frame	IEC 100			
Serial no.				
Nounting	B14A			
Degree of Protection	55	IP		
	160°C			
	3 x 230/400		Plus/Minus 5% a	icc to IEC60034
	230V 13,4 400V 7,9			
		A		
	32	1400 mm		
ocked rotor torque I _S /I _N				
		Nm		
		Nm		
Speed at minimum torque		rpm		
· · · · · · · · · · · · · · · · · · ·		Current A	Efficiency %	Power factor
PLL determined from residual loss				
Any inclusion starting time from hot & cold	Start	e/e		
	F	3/3		
		°C		
Altitude				
Cooling Method	411	IC	Fan	
		m³/hr		
Bearing DE/NDE	6206 ZZ			
Dil Quantity for bearings		l/min		
Type of Grease				
	A)		at load	
		kgm²		
0				
	тор			
•				
Veight of rotor		ka		
Total weight of motor	21	kg		
Dimension drawing no.		-		
Painting specification		Norsok/Other	r	
			ļ	
rs				
The Constitution of the second line of the second l				
Ex Certificat issued by			1	
Ex Certificat number				
-				
	finding temp. sensors finding Connection ated output P_N ated voltage U_N lowable starting voltage ated frequency f_N ated current I_N o-load current ervice factor ype of duty ated speed n_N ominal torque T_N bocked rotor torque T_s/T_N aximum torque T_{max}/T_N inimum torque T_{min}/T_N boed at minimum torque boad characteristics (IEC 60034-2-1:20) LL determined from residual loss aximum starting time from hot & cold sulation class / Temperature class mbient temperature titude booling Wathod booling Wathod booling Wathod booling Wathod booling Wethod booling Wethod booling Wethod booling Wethod booling Water Flow Rate bearing DE/NDE il Quantity for bearings ype of Grease bound pressure level at 1 meter LP dB(boment of inertia J = 1/4 GD2 alancing ake/Type of vibration detectors bosition of terminal box erminal box meterial erminal box meterial erminal box entries; no, dimens. umber of power terminals irection of rotation feight of motor bool weight of motor imension drawing no.	finding temp. sensors $160^{\circ}C$ inding Connection3ated output P_N 3ated output P_N 3 x 230/400lowable starting voltage50ated frequency f_N 50ated current I_N 230V 13,4 400V 7,9o-load currentenvice factorpe of dutyS2ated speed n_N 50ominal torque T_N size and the second secon	Inding temp. sensors160°CInding ConnectionStar/Deltaated output P_N 3kWated output P_N 3 x 230/400Vlowable starting voltage50Hzated frequency f_N 50Hzated current I_N 230V 13,4 400V 7,9Ao-load currentAApe of dutyS21400 rpmated speed n_N Nmopic of core T_S/T_N Nmated current T_N Nmated speed n_N Nmated rouge T_N Nmated speed n_N Nmated rouge T_N Nmated rouge T_N Nmated core of the transform of the tresion of the transform of the transform	Inding temp. sensors160°CStar/Deltainding ConnectionStar/Deltaitinding Connection3ated output P_h 3ated outge U_h 3 x 230/400lowable starting voltage%Unated frequency f_h 50bolast del frequency f_h 60bolast del speed n_h Mmcked rotor torque T_{T_H} Nmaximum torque $T_{mat} T_h$ Nmbeed at minimum torquerpmbalance trackits (IEC 60034-2-1:2007)Load %L determined from residual loss100tude100mains tarting time from hot & coldStartstartstartaximum starting time from hot & cold100tude1000mains DE/NDE6206 ZZi Quantity for bearingsI/mini Quantity for bearingsI/min <tr< td=""></tr<>